Numerical Investigation on Accuracy Improvement of Permanent Magnet Method for Measuring j_C in High-Temperature Superconducting Film^{*)}

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Possibility of the accuracy improvement in the permanent magnet method for measuring the critical current density of a high-temperature superconducting (HTS) thin film has been investigated numerically. To this end, a numerical code has been developed for analyzing the shielding current density in an HTS sample. By using the code, the permanent magnet method has been reproduced numerically. The results of computations show that, by using the magnet strength B_F as large as possible, the high accuracy can be assured with little effort. Furthermore, in order to improve the measurement accuracy of the critical current density near the film edge, it is necessary to use the magnet with the smallest radius.

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1. Introduction

As is well known, flywheel systems and fusion reactor systems have been developed with high-temperature superconductors (HTSs), and HTS materials have various characteristic parameters. Especially, a critical current density $j_{\rm C}$ is one of the most important parameters of the HTS. Therefore, it is necessary to accurately measure the critical current density $j_{\rm C}$ in an HTS sample.

The standard four-probe method has been generally used for measuring a critical current density j_C of the HTS sample. However, this method may leads not only to the destruction of a sample surface but also to the degradation of superconducting characteristics. For this reason, a non-contact method has been so for desired for measuring the critical current density. Currently, the popular method is the inductive method proposed by Claassen *et al.* [1].

As a novel noncontact method for measuring $j_{\rm C}$, Ohshima *et al.* proposed the permanent magnet method for measuring the critical current density $j_{\rm C}$ in a HTS thin film [2, 3]. While moving a permanent magnet placed above an HTS thin film, they measure an electromagnetic force acting on the film. Consequently, they found that the maximum repulsive force $F_{\rm M}$ is roughly proportional to the critical current density $j_{\rm C}$. This means that $j_{\rm C}$ can be estimated by measuring $F_{\rm M}$. Recently, $j_{\rm C}$ -distributions are evaluated by using this method [4].

In order to numerically reproduce the permanent mag-

net method, a numerical code has been developed by analyzing the time evolution of a shielding current density in the HTS thin film [5]. By using the code, the results of computations indicate that the measurement accuracy is degraded near the HTS film edge. However, it is found that the maximum repulsive force is roughly proportional to the critical current density j_C [5] near the film edge. In conclusion, the critical current density j_C near the film edge can be estimated from the proportionality constant determined in advance from the resulting j_C - F_M line. However, the determination of proportionality constant wastes time because it is necessary to calculate the proportionality constants as a function of the magnet position. Therefore, the accuracy improvement is desired near the film edge.

The purpose of the present study is to investigate the possibility of the accuracy improvement by changing the operating conditions in the permanent magnet method.

2. Governing Equations

In Fig. 1, we show a schematic view of a permanent magnet method. A cylindrical permanent magnet of the radius $r_{\rm m}$ and the height $h_{\rm m}$ is placed above a square-shaped HTS thin film of the length *a* and the thickness *b*. Furthermore, we adopt the Cartesian coordinate system $\langle O : \boldsymbol{e}_x, \boldsymbol{e}_y, \boldsymbol{e}_z \rangle$, where *z*-axis is the thickness direction, and the origin O is the centroid of an HTS film.

A distance *L* between a magnet bottom and a film surface is controlled as follows:

1. From $L = L_{max}$ to $L = L_{min}$, the magnet is moved to

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Fig. 1 A schematic view of a permanent magnet method.

the film at the constant speed $v = (L_{\text{max}} - L_{\text{min}})/\tau_0$. Here, τ_0 is a constant.

2. From $L = L_{\min}$ to $L = L_{\max}$, the magnet is moved away from the film at the same speed v.

For determining a magnet strength, we adopt a magnetic flux density B_F at for the case with $L = L_{min}$ and (x, y, z) = (0, 0, b/2). In addition, the *xy*-coordinates the magnet center is defined by (x_m, y_m) .

As usual, we assume that the thin-layer approximation [6]: since the thickness of the HTS is sufficiency thin, a shielding current density can hardly flow in the thickness direction. In the following, an HTS film cross-section passing through z = const. and its boundary are denoted by Ω and $\partial\Omega$, respectively.

Under the above assumptions, a shielding current density in an HTS is written as $\mathbf{j} = (2/b)\nabla S \times \mathbf{e}_z$, and the behavior of the scalar function $S(\mathbf{x}, t)$ is governed by the following integro-differential equation [6]:

$$\begin{aligned} &\mu_0 \frac{\partial}{\partial t} \left[\int_{\Omega} d^2 \mathbf{x}' \mathcal{Q} \left(\left| \mathbf{x} - \mathbf{x}' \right| \right) S \left(\mathbf{x}', t \right) + \frac{2}{b} S(\mathbf{x}, t) \right] \\ &+ \frac{\partial}{\partial t} \left\langle \mathbf{B} \cdot \mathbf{e}_z \right\rangle + (\nabla \times \mathbf{E}) \cdot \mathbf{e}_z = 0. \end{aligned}$$
(1)

Here, x is defined by $x \equiv xe_x + ye_y$. In addition, am angle brackets $\langle \rangle$ are an average operator over the thickness of the HTS, and it is given by

$$\langle f \rangle \equiv \frac{1}{b} \int_{-b/2}^{b/2} f dz.$$
 (2)

Incidentally, the explicit form of a function $Q(\mathbf{x}, \mathbf{x}')$ is described in Ref. [6].

The shielding current density j is closely related to the electric field E. The relation is expressed by the *J*-*E* constitute equation: E = E(|j|)[j/|j|]. As a function E(j), we use the power law: $E(j) = E_C[j/j_C]^N$, where E_C is a critical electric field and N is a constant.

For the initial and boundary conditions to (1), we assume S = 0 at t = 0 and S = 0 on $\partial\Omega$. By solving the initial-boundary problem of (1), we can obtain the time evolution of a shielding current density. Throughout the present study, the physical and geometric parameters are fixed as follows: a = 40 mm, b = 200 nm, $y_{\text{m}} = 0 \text{ mm}$, $h_{\text{m}} = 3 \text{ mm}$, $\tau_0 = 39 \text{ s}$, $L_{\text{max}} = 20 \text{ mm}$, $L_{\text{min}} = 0.5 \text{ mm}$, $E_{\text{C}} = 0.1 \text{ mV/m}$, and N = 20.



Fig. 2 Dependence of the electromagnetic force F_z on the distance L for the case with $x_m = 0$ mm, $r_m = 2.5$ mm, $B_F = 0.2$ T, and $j_C = 4.5$ MA/cm².

3. Numerical Results

In order to simulate the permanent magnet method, a numerical code has been developed for solving the initialboundary problem of (1). The code can be executed by specifying an assumed critical current density $j_{\rm C}$. In the present study, we use the assumed value, 0.1 MA/cm² $\leq j_{\rm C} \leq 10$ MA/cm², where the assumed values of $j_{\rm C}$ derives from Ohshima's experimental results [2, 3].

In Fig. 2, we show the dependence of the electromagnetic force F_z on the distance L. We see from this figure that the F_z has a hysteresis curve. A repulsive force is acting on the film for $0 \le t \le \tau_0$, whereas an attractive force occurs for $\tau_0 < t \le 2\tau_0$. By extrapolating the repulsive force, we can evaluate the electromagnetic force at L = 0 mm (see Fig. 2). Hereafter, this force is called the maximum repulsive force, and it is denotes by $F_{\rm M}$.

3.1 Influence of magnet strength on accuracy

Let us first investigate the influence of the relation between the critical current density $j_{\rm C}$ and the maximum repulsive force $F_{\rm M}$ for the various strength $B_{\rm F}$. In Fig. 3, we indicate that the dependence of the critical current density $j_{\rm C}$ on the maximum repulsive force $F_{\rm M}$. We see from this figure that, when the magnet strength is $B_{\rm F} = 0.01$ T and 0.03 T, the proportional relations between $j_{\rm C}$ and $F_{\rm M}$ do not hold for the case with a high $j_{\rm C}$. The reason is as follows: in order to hold the proportional relation between $j_{\rm C}$ and $F_{\rm M}$, an inequality $\max_{\mathbf{x} \in \mathcal{O}} |\mathbf{j}(\mathbf{x})| / j_{\rm C} \ge 1$ must be satisfied numerically. In other words, the magnetic shielding of the HTS is broken down and, simultaneously, the HTS has the normal conducting state. The results of the computations show that, for $B_{\rm F} = 0.01$ T and 0.03 T, the inequality is not satisfied. On the other hand, $j_{\rm C}$ is almost proportional to $F_{\rm M}$ for the case with $j_{\rm C} \leq 3.0 \text{ MA/cm}^2$ for each $B_{\rm F}$. As a result, for $j_{\rm C} \leq 3.0 \text{ MA/cm}^2$, a proportionality constant can be obtained even when the magnet strength $B_{\rm F}$ is low.

In the present study, a proportionality constant is determined from $j_{\rm C}$ - $F_{\rm M}$ line for $j_{\rm C} \le 1.0$ MA/cm² by using the least-square method. Therefore, an estimated formula



Fig. 3 Dependence of the critical current density $j_{\rm C}$ on the maximum repulsive force $F_{\rm M}$ for the case with $x_{\rm m} = 0$ mm and $r_{\rm m} = 2.5$ mm. Here, the solid lines show the estimated value of the critical current density $j_{\rm C}^*$.



Fig. 4 Dependence of the relative error ε on the maximum repulsive force $F_{\rm M}$ for the case with $x_{\rm m} = 0$ mm and $r_{\rm m} = 2.5$ mm.

of the critical current density $j_{\rm C}$ can be defined as

$$j_{\rm C}^* \equiv K(B_{\rm F}, r_{\rm m})({\rm MA} \cdot {\rm cm}^{-1} \cdot {\rm gf})(F_{\rm M}/b), \qquad (3)$$

where K is the proportionality constant.

Next, in order to quantitatively examine the difference between $j_{\rm C}^*$ and $j_{\rm C}$, we define a relative error: $\varepsilon \equiv |j_{\rm C}^* - j_{\rm C}|/|j_{\rm C}|$. In Fig. 4, we show that the dependence of the relative error ε on the maximum repulsive force $F_{\rm M}$. We see from this figure that the relative error ε increases with $F_{\rm M}/b$. In particular, the relative error ε drastically increases with decreasing $B_{\rm F}$. From these results, we assume that there exists the limit of the $j_{\rm C}$ -measurement for each $B_{\rm F}$.

Finally, we investigate the limit of the maximum repulsive force $F_{\rm M}$. For this purpose, we use the acceptable error $\varepsilon_{\rm a} = 1.5 \,\%$ (see Fig. 4) and, subsequently, we determine the limit of the maximum repulsive force $F_{\rm M}^*$ from $\varepsilon_{\rm a}$. In Fig. 5, we indicate the limit of the maximum repulsive force $F_{\rm M}^*$ on the magnet strength $B_{\rm F}$. From this result, this figure can serve as a guide to the measurement accuracy $j_{\rm C}$ in the permanent magnet method. In fact, if a measured $F_{\rm M}$ for a certain $B_{\rm F}$ satisfy the inequality $F_{\rm M} \leq F_{\rm M}^*$, the accuracy with $\varepsilon \leq 1.5 \,\%$ is assured. For the case with $F_{\rm M} > F_{\rm M}^*$, it is only necessary to remeasure $F_{\rm M}$ by changing the strength $B_{\rm F}$. We conclude that, by using the mag-



Fig. 5 Dependence of the limit of maximum repulsive force $F_{\rm M}^*$ on the magnet strength $B_{\rm F}$ for the case with $x_{\rm m} = 0$ mm and $r_{\rm m} = 2.5$ mm.



Fig. 6 Dependence of the relative error ε_r on the magnet position x_m .

net strength $B_{\rm F}$ as large as possible, the high accuracy can be assured with little effort. However, it is found that, by changing the strength $B_{\rm F}$, the accuracy improvement near the film edge cannot be achieved.

3.2 Accuracy improvement

In this subsection, we investigate whether the radius $r_{\rm m}$ of the magnet affect the measurement accuracy of the critical current density $j_{\rm C}$. To this end, we assume that an HTS film has a uniform $j_{\rm C}$ -distribution, and $j_{\rm C}$ and $B_{\rm F}$ is fixed as $j_{\rm C} = 4.5$ MA/cm² and $B_{\rm F} = 0.3$ T, respectively. Therefore, the proportional relation between $j_{\rm C}$ and $F_{\rm M}$ is given by

$$j_{\rm C}^{\rm N} = \alpha(r_{\rm m})({\rm MA} \cdot {\rm cm}^{-1} \cdot {\rm gf})(F_{\rm M}/b). \tag{4}$$

For the parameters in the present study, the proportionality constants are α (1.5 mm) = 1.82×10^{-8} ; α (2.5 mm) = 8.23×10^{-8} ; α (3.5 mm) = 4.64×10^{-9} ; α (4.5 mm) = 2.91×10^{-9} . By substituting the resulting maximum repulsive force $F_{\rm M}$ into (4), an estimated value of the critical current density is determined.

Let us investigate the influence of the radius $r_{\rm m}$ on the accuracy. As a criterion of the accuracy, we define a relative error: $\varepsilon_{\rm r} \equiv |j_{\rm C}^{\rm N} - j_{\rm C}|/|j_{\rm C}|$. In Fig. 6, we show the dependence of the relative error $\varepsilon_{\rm r}$ on the magnet position $x_{\rm m}$ for the various radius $r_{\rm m}$. This figure indicates that the relative



Fig. 7 The spatial distributions of the magnetic flux density $\langle B_z \rangle$ for the case with $x_m = 0$ mm.



Fig. 8 The spatial distributions of the shielding current density for the case with $x_{\rm m} = 17$ mm.

error ε_r increases with the magnet position x_m . Moreover, ε_r decreases with r_m for $x_m \leq 19 \text{ mm}$ (e.g. for the case with $x_m = 17 \text{ mm}$, the relative error is $\varepsilon_r = 19.7 \%$ for $r_m = 1.5 \text{ mm}$; $\varepsilon_r = 36.5 \%$ for $r_m = 4.5 \text{ mm}$). Consequently, the measurement accuracy of $j_{\rm C}$ near the film edge improves by using a smaller radius $r_{\rm m}$.

Let us numerically investigate why the measurement accuracy of j_C degrades remarkably. In Fig. 7, we show the spatial distributions of the magnetic flux density $\langle B_z \rangle$ for the various radius r_m . Here, r denotes the r-coordinate for the cylindrical coordinate (r, θ, z) . This figure shows that the applied area of the magnetic flux density $\langle B_z \rangle$ decreases with the radius r_m . As a result, the area of the shielding current density decreases with radius r_m (see Fig. 8). This figure shows that, for $r_m = 1.5$ mm, the distribution the shielding current density almost has axisymmetric. On the other hand, for $r_m = 4.5$ mm, j has the strongly nonaxisymmetric distribution, because an HTS edge significantly affects the distribution of j. Consequently, in order to enhance the measurement accuracy of j_C near the film edge, it is necessary to use the magnet with the smallest radius.

4. Conclusion

We investigate the possibility of the accuracy improvement by changing the operating conditions. Conclusions obtained in the present study are summarized as follows:

- 1. By using the magnet strength B_F as large as possible, the high accuracy can be assured with little effort. As a result, it may be possible to reduce the time for measuring the critical current density j_C .
- 2. In order to enhance the measurement accuracy of $j_{\rm C}$ near the film edge, it is necessary to use the magnet with the smallest radius.

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