Numerical Simulation of Contactless Methods for Measuring $j_{\rm C}$ Distribution of High Temperature Superconducting Thin Film

Teruou TAKAYAMA, Atsushi KAMITANI and Hiroaki NAKAMURA¹⁾

Yamagata University, Yamagata 992-8510, Japan ¹⁾National Institute for Fusion Science, Gifu 509-5292, Japan (Received 8 December 2010 / Accepted 22 February 2010)

The inductive method and the permanent magnet method for measuring the critical current density in a hightemperature superconducting (HTS) thin film have been investigated numerically. For this purpose, a numerical code has been developed for analyzing the time evolution of the shielding current density in a HTS sample. The results of computations show that, in the inductive method, the critical current density near the film edge cannot be accurately evaluated. On the other hand, it is found that, in the permanent magnet method, even if the magnet is placed near the film edge, the maximum repulsive force is roughly proportional to the critical current density. This means that the critical current density near the film edge can be estimated from the resulting proportionality constants.

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1. Introduction

High-temperature superconductors (HTSs) can be used in standard applications such as power-transmission cables, flywheel systems and fusion reactor systems. As is well known, HTS materials have various characteristics to keep the superconducting state. In particular, since the critical current density j_C is one of most important parameters characterizing a superconducting property, it is necessary to accurately measure j_C .

The standard four probe method is generally used to measure the critical current density $j_{\rm C}$. In the method, a HTS sample is coated by gold or silver, and subsequently, it should be heat-treated. This process may lead to not only the destruction of the HTS but also the degradation of the HTS characteristics. Therefore, a contactless method has been so far desired for measuring $j_{\rm C}$.

Claassen *et al.* proposed a contactless method for measuring the critical current density j_C [1]. By applying an ac current $I(t) = I_0 \sin 2\pi f t$ to a small coil placed just above a HTS thin film, they monitored a harmonic voltage induced in the coil. From the experimental results, they found that, only when a coil current I_0 exceeds a threshold current I_T , the third-harmonic voltage V_3 develops suddenly. Moreover, it was also revealed that j_C can be evaluated from I_T . This method is called the inductive method and is widely used for the determination of j_C -distributions. On the other hand, Mawatari *et al.* elucidated the inductive method on the basis of the critical state model [2]. As a result, they derived a theoretical formula for the relation between j_C and I_T . In contrast, Ohshima *et al.* proposed a novel contactless method [3, 4]. While moving a permanent magnet placed above a HTS film, they measure an electromagnetic force acting on the film. As a result, they found that the maximum repulsive force $F_{\rm M}$ is almost proportional to the critical current density $j_{\rm C}$. This means that $j_{\rm C}$ can be estimated by measuring $F_{\rm M}$. This method is called the permanent magnet method and is recently used for the measurement of the $j_{\rm C}$ -distribution [5].

In order to simulate two types of contactless methods, a numerical code has been developed by analyzing the time evolution of a shielding current density in a HTS thin film [6]. By using the code, we have succeeded in reproducing the contactless methods. However, since we adopt the cylindrical coordinate in the code [6], the center of the coil and magnet is located at just above the origin. Therefore, it is impossible to evaluate a spatial distribution of j_C in a HTS sample by use of the code.

The purpose of the present study is to develop a numerical code for analyzing the time evolution of the shielding current density in a HTS thin film for the case with the non-axisymmetric model. In addition, we simulate the inductive method and the permanent magnet method by using the code, and investigate the influence of the coil and the magnet position on the determination of the $j_{\rm C}$ distribution.

2. Governing Equations

In measuring a critical current density $j_{\rm C}$ by means of the contactless methods, a time-dependent magnetic field is applied to a HTS sample. Throughout the present



Fig. 1 A schematic view of contactless methods for measuring the critical current density j_C .

study, we assume that a magnetic field \boldsymbol{B}/μ_0 is applied to a square-shaped HTS thin film of the length *a* and the thickness 2ε (see Fig. 1). Furthermore, we adopt the Cartesian coordinate system $\langle O : \boldsymbol{e}_x, \boldsymbol{e}_y, \boldsymbol{e}_z \rangle$, where *z*-axis is the thickness direction. Note that, in the inductive method, the origin O is chosen at the center of a HTS upper surface. In the permanent magnet method, O is taken at the centroid of a HTS.

As usual, we assume that the thin-layer approximation: since the thickness of the HTS is sufficiency thin, a shielding current density can hardly flow in the thickness direction. Hereafter, a HTS film cross-section passing through z = const. and its boundary are denoted by Ω and $\partial \Omega$, respectively.

Under the above assumptions, a shielding current density in a HTS is written as

$$\boldsymbol{j} = \frac{1}{\varepsilon} \nabla S \times \boldsymbol{e}_{z},\tag{1}$$

and the behavior of the scalar function $S(\mathbf{x}, t)$ is governed by the following integro-differential equations [7]:

$$\mu_{0} \frac{\partial}{\partial t} \left[\int_{\Omega} d^{2} \mathbf{x}' Q \left(|\mathbf{x} - \mathbf{x}'| \right) S \left(\mathbf{x}', t \right) + \frac{1}{\varepsilon} S \right] \\ + \frac{\partial}{\partial t} \left\langle \mathbf{B} \cdot \mathbf{e}_{z} \right\rangle + \left(\nabla \times \mathbf{E} \right) \cdot \mathbf{e}_{z} = 0.$$
(2)

Here, **x** is defined by $\mathbf{x} \equiv x\mathbf{e}_x + y\mathbf{e}_y$, and $\langle \rangle$ is an average operator over the thickness of the HTS. The explicit form of $Q(\gamma)$ [7] is

$$Q(\gamma) = -\frac{1}{4\pi\varepsilon^2} \left(\frac{1}{\gamma} - \frac{1}{\sqrt{\gamma^2 + 4\varepsilon^2}} \right).$$
(3)

As is well known, the shielding current density j is closely related to the electric field E. The relation is expressed by the *J*-*E* constitute equation:

$$\boldsymbol{E} = E(|\boldsymbol{j}|)\boldsymbol{j}/|\boldsymbol{j}|. \tag{4}$$

As a function E(j), we employ the power law [8]:

$$E(j) = E_{\rm C}(j/j_{\rm C})^{16},$$
(5)



Fig. 2 A schematic view of an inductive method.

where $E_{\rm C}$ is a critical electric field. In the following, we assume that a HTS film has a uniform $j_{\rm C}$ -distribution.

For applying the initial and boundary conditions to (2), we assume S = 0 at t = 0 and S = 0 on $\partial\Omega$. By solving the initial-boundary problem of (2), we can obtain the time evolution of a shielding current density. A numerical code has been developed for solving the initial-boundary problem of (2). In order to simulate two types of contactless methods, the code can be executed by specifying an assumed critical current density j_C and a magnetic field **B** generated by a coil or a permanent magnet.

3. Simulation of Inductive Method

By performing the theoretical calculation based on the critical state model, Mawatari *et al.* have derived the following formula [2]

$$j_{\rm C}^{\rm N} = F(r_{\rm max})I_{\rm T}/\varepsilon,\tag{6}$$

where $j_{\rm C}^{\rm N}$ is an estimated value of the critical current density $j_{\rm C}$. $F(r_{\rm max})$ is the maximum of a primary coil-factor function F(r) [2] which can be determined from the configuration of the coil and the HTS. Furthermore, $I_{\rm T}$ is a lower limit of a coil current I_0 above which the third-harmonic voltage V_3 begins to develop. For estimating $I_{\rm T}$, we use the conventional voltage criterion: $V_3 = 0.1 \,\mathrm{mV} \Leftrightarrow I_0 = I_{\rm T}$ [2] in the present study.

In the inductive method, the time-dependence magnetic filed B/μ_0 is generated by applying an ac current $I(t) = I_0 \sin 2\pi ft$ to an N_c -turn coil placed just above a HTS thin film. For determining the coil position, the *xy* coordinates of the center of coil is given by $(x, y) = (x_c, y_c)$ (see Fig. 2). Furthermore, the cross-section of the coil is expressed as $D = \{(z, r) : |z - Z_c| \le H/2, |r - R_c| \le W/2\}$ with the cylindrical coordinate (r, θ, z) . Here, *H* and *W* are height and width of the cross-section, respectively, and its center is $(z, r) = (Z_c, R_c)$. Throughout the present section, the parameters are fixed as follows: a = 20 mm, $2\varepsilon = 600$ nm, $x_c = 0$ mm, $N_c = 400$, f = 1 kHz, $E_c = 1$ mV/m. For the above configuration, we obtain $F(r_{max})$



Fig. 3 Dependence of the third-harmonic voltage V_3 on the coil current I_0 for the case with $j_{\rm C} = 1$ MA/cm².

 $6.23 \times 10^4 \,\mathrm{m}^{-1}$.

Under the above conditions, let us investigate the influence of the coil position on the determination of the $j_{\rm C}$ distribution. To this end, the *y*-coordinate $y_{\rm c}$ of the center of the coil is changed from 0 mm to 10 mm.

First, for estimating the threshold current $I_{\rm T}$, the thirdharmonic voltage V_3 is calculated as functions of the coil current I_0 and is plotted in Fig. 3. We see from this figure that, for $y_c = 0$ mm, V_3 begins to develop from a certain value of I_0 , and after that, V_3 monotonously increases with I_0 . By applying the voltage criterion to the I_0 - V_3 curve for $y_c = 0$ mm, we get $I_{\rm T} = 47.6$ mA. By substituting the value of $I_{\rm T}$ to (6), we can obtain $j_{\rm C}^{\rm N} = 0.99$ MA/cm². This value fairly agrees with the assumed critical current density $j_{\rm C} = 1$ MA/cm². On the other hand, it is found that, for $y_c = 10$ mm, the behavior of V_3 greatly differs in $y_c = 0$ mm. According to the voltage criterion, the value of $I_{\rm T}$ is 19.3 mA for $y_c = 10$ mm.

Next, let us investigate the relation between the threshold current $I_{\rm T}$ and the critical current density $j_{\rm C}$. To this end, $I_{\rm T}$ is calculated as functions of $j_{\rm C}$ and is depicted in the inset of Fig. 4. We see from this figure that, for $y_{\rm c} = 0$ mm, $I_{\rm T}$ is roughly proportional to $j_{\rm C}$. This tendency quantitatively agrees with Mawatari's theoretical formula (6). On the other hand, it is found that, for $y_{\rm c} = 10$ mm, the proportional relation between $I_{\rm T}$ and $j_{\rm C}$ no longer hold.

Finally, let us numerically investigate a limit of the measurement of the critical current density $j_{\rm C}$. In order to quantitatively evaluate the accuracy of the threshold current $I_{\rm T}$, we define a relative error

$$\varepsilon_{\rm r} \equiv \|I_{\rm T}^{\rm A} - I_{\rm T}^{\rm N}\|_{\infty} / \|I_{\rm T}^{\rm A}\|_{\infty}. \tag{7}$$

Here, $I_{\rm T}^{\rm N}$, a estimated value of $I_{\rm T}$, is obtained from the voltage criterion, and $I_{\rm T}^{\rm A}$, a theoretical value, is expressed as $I_{\rm T}^{\rm A} = j_{\rm C}\varepsilon/F(r_{\rm max})$. Furthermore, $||f||_{\infty}$ is denoted by $||f||_{\infty} = \max_{j_{\rm C}\in J} |f(j_{\rm C})|$. Here, J is defined by $J \equiv$



Fig. 4 Dependence of the relative error ε_r on the y-coordinate y_c of the coil. The inset shows that dependence of the threshold current I_T on the critical current density j_C . Here, Δ : $y_c = 0$ mm, \mathbf{v} : $y_c = 10$ mm.

 $\{0.1 \text{ MA/cm}^2 \le j_C \le 10 \text{ MA/cm}^2\}$. The relative error ε_r is calculated as a function of y_c and is plotted in Fig. 4. We see from this figure that, for $y_c > 7.5$ mm, the accuracy of the inductive method is drastically degraded with y_c . An important point is that, for $y_c = 7.5$ mm, the sum of y_c and the outer radius $R_c + W/2$ is equal to a/2. From this result, we conclude that, until the outer radius of the coil is equal to the film edge, the critical current density can be accurately evaluated from Mawatari's theoretical formula.

4. Simulation of Permanent Magnet Method

In the permanent magnet method, the timedependence magnetic field B/μ_0 is generated by a cylindrical permanent magnet placed above a HTS thin film. Here, the radius and the height of the magnet are r_m and h_m , respectively, and the *xy* coordinates of the center of the magnet is denoted by $(x, y) = (x_m, y_m)$. A distance *L* between a magnet bottom and a film surface is controlled as follows:

- (i) From $L = L_{\text{max}}$ to $L = L_{\text{min}}$, the magnet is moved toward the film at the constant speed: $v = (L_{\text{max}} - L_{\text{min}})/\tau_0$. Here, τ_0 is a constant.
- (ii) From $L = L_{min}$ to $L = L_{max}$, the magnet is moved away from the film at the same speed v.

Furthermore, for determining the strength of the magnet, we employ a magnetic flux density $B_{\rm F}$ at $(x, y, z) = (0, 0, \varepsilon)$ for the case with $L = L_{\rm min}$. Throughout the present section, the parameters are fixed as follows: a = 40 mm, $2\varepsilon =$ 200 nm, $x_{\rm m} = 0$ mm, $r_{\rm m} = 2.5$ mm, $h_{\rm m} = 3$ mm, $\tau_0 = 39$ s, $L_{\rm max} = 20$ mm, $L_{\rm min} = 0.5$ mm, $E_{\rm C} = 0.1$ mV/m, $B_{\rm F} = 0.3$ T.

Under the above conditions, we investigate the influence of the magnet position on the determination of the $j_{\rm C}$ -distribution. For this purpose, the *y*-coordinate $y_{\rm m}$ of



Fig. 5 Dependence of the electromagnetic force F_z on the distance L for the case with $j_{\rm C} = 3.85 \,{\rm MA/cm^2}$.

the center of the magnet is changed from 0 mm to 20 mm.

Let us first investigate an electromagnetic force F_z acting on the film. For the various values of y_m , the electromagnetic force is calculated as functions of the distance L and are depicted in Fig. 5. We see from this figure that a repulsive force gradually increases as the magnet moves toward the film ($0 \le t \le \tau_0$). On the other hand, an attractive force decreases to zero when the magnet moves away from the film ($\tau_0 < t \le 2\tau_0$). These tendencies do not change regardless of the magnet position. The electromagnetic force for L = 0 can be easily determined by extrapolating the L- F_z curve (see Fig. 5). In the following, this value is called a maximum repulsive force F_M .

Next, we investigate the relation between the maximum repulsive force $F_{\rm M}$ and the critical current density $j_{\rm C}$. Note that the experimental results were obtained for the case with only $y_{\rm m} = 0 \,{\rm mm}$ [3, 4]. For various values of $y_{\rm m}$, $F_{\rm M}$ is evaluated as functions of $j_{\rm C}$ and is plotted in Fig. 6. This figure indicates that, for $y_{\rm m} = 0 \,{\rm mm}$, $F_{\rm M}$ increases in proportion to $j_{\rm C}$. This result is in qualitatively agreement with Ohshima's experimental one. On the other hand, the results of computations show that, even when the magnet is located at $y_{\rm m} = 19 \,{\rm mm}$ and 20 mm, $F_{\rm M}$ is almost proportional to $j_{\rm C}$. In other words, the relation can be expressed as $j_{\rm C} = K(x_{\rm m}, y_{\rm m})(F_{\rm M}/2\varepsilon)$, where K is a proportionality constant.

From this result, we conclude that, even if the magnet is placed near the film edge, the critical current density $j_{\rm C}$ can be determined. Therefore, the $j_{\rm C}$ -distribution in the HTS film can be estimated from the proportionality constants determined by the resulting $F_{\rm M}$ - $j_{\rm C}$ lines.

5. Conclusion

We have developed a numerical code for analyzing the time evolution of the shielding current density in a HTS sample for the case with the non-axisymmetric model. By using the code, simulating the inductive method and the permanent magnet method, we investigate the influence of



Fig. 6 Dependence of the critical current density $j_{\rm C}$ on the maximum repulsive force $F_{\rm M}$. Here, \diamond : $y_{\rm c} = 0$ mm, $\mathbf{\nabla}$: $y_{\rm m} = 19$ mm, \triangle : $y_{\rm m} = 20$ mm.

the coil and the magnet position on the determination of the distribution of the critical current density $j_{\rm C}$. Conclusions obtained in the present study are summarized as follows:

- (1) In the inductive method, the critical current density $j_{\rm C}$ near the film edge cannot be accurately measured. In other words, until the outer radius of the coil is equal to the film edge, $j_{\rm C}$ can be evaluated from Mawatari's theoretical formula.
- (2) In the permanent magnet method, even if the magnet is located near the film edge, the maximum repulsive force F_M is almost proportional to j_C. From this result, j_C near the film edge can be estimated from the proportionality constant determined with the resulting F_M j_C lines.

Therefore, we conclude that the measurement of $j_{\rm C}$ near the film edge is suitable for the permanent magnet method.

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