# Gradient-Length Analysis of the Magnetized Plasma-Wall Transition (MPWT) 

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(Received: 2 September 2008 / Accepted: 15 March 2009)
For analytic simplicity, the magnetized plasma-wall transition (MPWT) layer occurring, e.g., near tokamak divertors, is usually split into three sublayers: the Debye sheath (DS), the magnetic presheath (MPS) and the collisional presheath (CPS), with characteristic (indicated by superscript "ch") length scales $\lambda_{D}^{c h}$ (electron Debye length), $\rho_{i}^{c h}$ (ion gyro-radius) and $\lambda_{c}^{c h}$ (smallest relevant ion collision length), respectively. The values of these characteristic lengths are taken at certain characteristic points of the respective sublayers, whereas the gradient lengths vary with position. We introduce a new method for systematically investigating the behavior of gradient-length scales in the MPWT. The gradient lengths are used to replace in the fluid equations all gradients, which transforms these equations into an algebraic system. Here, as a first example of application, this method is applied to the MPWT in the asymptotic three-scale (A3S) limit $\lambda_{D}^{c h} \ll \rho_{i}^{c h} \ll \lambda_{c}^{c h}$.

Keywords: Plasma-wall transition, Debye sheath, magnetic presheath, collisional presheath, plasma-wall interaction, tokamak plasma.

## 1. Introduction

In the presence of a magnetic field oblique to the wall, the plasma-wall transition (PWT) layer can be divided into three regions, namely: Debye sheath (DS), magnetic presheath (MPS) and collisional presheath (CPS) [1]. In the classical PWT problem without magnetic field, monotonicity of the electric potential requires fulfillment of the Bohm condition at the interface between the CPS (with the characteristic collisional length $\sim \lambda_{c}^{c h}$, chosen appropriately) and the $\operatorname{DS}\left(\sim \lambda_{D}^{\text {ch }}\right)$. Chodura was the first to investigate the MPS in an oblique magnetic field without any collisional effects [2]. The MPS was found to scale with the characteristic ion gyro-radius $\rho_{i}^{c h}$ For the limiting ordering of the scale variables, i.e., $\lambda_{D}^{c h} \ll \rho_{i}^{c h} \ll \lambda_{c}^{c h} \quad$, the problem contains three distinguished scales and, in this "asymptotic three-scale (A3S) limit", i.e. for $\varepsilon_{D m} \equiv \lambda_{D}^{c h} / \rho_{i}^{c h} \rightarrow 0 \quad$ and $\varepsilon_{m c} \equiv \rho_{i}^{c h} / \lambda_{c}^{c h} \rightarrow 0$, the DS can be characterized as collisionless and non-neutral, the MPS as collisionless and quasi-neutral ( $n_{i}=n_{e}$ ) [2] and the CPS as collisional and quasi-neutral.
The DS and the MPS regions are separated by the sheath edge. From the MPS side it is characterized by a field singularity, and from the DS side by the marginal form of the Bohm condition, $u_{z}=c_{s}=\left[k\left(T_{e}+\gamma T_{i}\right) / m_{i}\right]^{1 / 2} \quad\left(c_{s}\right.$ is the ion-sound velocity, $k$ is the Boltzmann constant, and $\gamma(z)$ is the polytropic coefficient [3]). The MPS-CPS boundary surface is referred to as the "MPS entrance". Below we show that quite in analogy with the unmagnetized PWT, the MPS entrance can be defined as a point were the electric field has a singularity from the CPS side. The condition imposed from the MPS side is similar
to the Bohm condition, but the ion velocity must be directed along the magnetic field line, $u_{\|}=c_{s}$. This is called as Bohm-Chodura condition. Hence the dominant effect of the MPS is to deflect the ion orbits, so that the velocity component $u_{z}$, can fulfill the Bohm condition at the DS entrance $[1,4]$.


Fig. 1 Structure of the MPWT

## 2. Model and basic equations

The problem is 1 D , with the $z$ axis perpendicular to the wall surface placed at $z=0$. The plasma occupies the region $z<0$. The electric potential $\Phi$ decreases towards the wall monotonically. The uniform magnetic field is assumed to be lying in the $x-z$ plane, making a small angle $\alpha$ with the wall. The thermal motion of the ions is neglected, $T_{i} \rightarrow 0$

To describe the magnetized plasma-wall transition (MPWT), we choose the following set of basic equations and definitions.

Ion continuity equation:

$$
\begin{equation*}
\frac{d}{d z}\left(n_{i} u_{z}\right)=v_{i} n_{e}-\kappa n_{e} n_{i}=v_{i r} n_{i} \tag{2.1}
\end{equation*}
$$

where $v_{i}$ is the "ionization frequency" (related to single electrons), $\kappa n_{e}$ is the "recombination frequency" (related to single ions), and

$$
\begin{equation*}
v_{i r}=v_{i} n_{e} / n_{i}-\kappa n_{e} \tag{2.2}
\end{equation*}
$$

is the combined frequency at which single ions appear ( $v_{i r}$ $>0)$ or disappear $\left(v_{i r}<0\right)$ due to the combined effect of ionization and recombination.

Ion momentum equations:

$$
\begin{align*}
& u_{z} \frac{d u_{x}}{d z}=\omega_{z} u_{y}-\bar{v} u_{x},  \tag{2.3}\\
& u_{z} \frac{d u_{y}}{d z}=\omega_{x} u_{z}-\omega_{z} u_{x}-\bar{v} u_{y},  \tag{2.4}\\
& u_{z} \frac{d u_{z}}{d z}=\frac{Z e}{m_{i}} E-\omega_{x} u_{y}-\frac{1}{m_{i} n_{i}} \frac{d p_{i}}{d z}-\bar{v} u_{z}, \tag{2.5}
\end{align*}
$$

with

$$
\begin{equation*}
\vec{\omega}=Z e \vec{B} / m_{i} \tag{2.6}
\end{equation*}
$$

the ion-cyclotron-frequency vector and

$$
\begin{equation*}
\bar{v}=v_{c x}+v_{i r} \tag{2.7}
\end{equation*}
$$

the combined charge-exchange, ionization and recombination frequency.

Electron density:

$$
\begin{equation*}
n_{e}=n_{e}(\phi) \tag{2.8}
\end{equation*}
$$

with $n_{e}(\phi)$ a given function. The related "electron screening temperature" is defined as

$$
\begin{equation*}
T_{e^{*}}=\frac{e n_{e}}{k\left(d n_{e} / d \phi\right)} \tag{2.9}
\end{equation*}
$$

and, hence, may be considered a given function of $\phi$ as well.

Poisson's equation:
$\frac{d E}{d z}=\frac{e}{\varepsilon_{0}}\left(Z n_{i}-n_{e}\right)$
Ion polytropic law:
$\frac{d p_{i}}{d z}=\gamma k T_{i} \frac{d n_{i}}{d z}$
Ideal-gas law:
$p_{i}=n_{i} k T_{i}$
Electric field:
$E=-d \phi / d z$
In addition we introduce the electric charge density

$$
\begin{equation*}
\rho=e\left(Z n_{i}-n_{e}\right) \tag{2.14}
\end{equation*}
$$

which, depending on convenience, may be used alternatively instead of $n_{e}$ as a variable.

## 3. Gradient-length representation

The length scales on which the various quantities vary with $z$ play a crucial role in determining the structure of the solutions. To formalize the related analysis, we rewrite gradients (i.e., derivatives with respect to $z$ ) in the form

$$
\begin{equation*}
\frac{d Q(z)}{d z}=\frac{Q^{g}(z)}{l_{Q}(z)} \tag{3.1}
\end{equation*}
$$

where $Q(z)$ may be any variable and $Q^{g}(z)$ is a typical value of $Q$ suitable for defining the "local gradient length" $l_{Q}$ at position $z$,

$$
\begin{equation*}
l_{Q}(z)=\frac{Q^{g}(z)}{d Q(z) / d z} \tag{3.2}
\end{equation*}
$$

which in general may assume positive or negative values. Clearly, $\left|l_{Q}\right|$ may be interpreted as the distance over which the change in $|Q|$ is of the order of $\left|Q^{g}\right|$. Accordingly, we can write

$$
\begin{array}{lll}
\frac{d u_{x}}{d z}=\frac{u_{x}^{g}}{l_{u x}}, & \frac{d u_{y}}{d z}=\frac{u_{y}^{g}}{l_{u y}}, & \frac{d u_{z}}{d z}=\frac{u_{z}^{g}}{l_{u z}} \\
\frac{d n_{i}}{d z}=\frac{n_{i}^{g}}{l_{n i}}, & \frac{d p_{i}}{d z}=\frac{p_{i}^{g}}{l_{p i}}, & \frac{d n_{e}}{d z}=\frac{n_{e}^{g}}{l_{n e}},  \tag{3.3}\\
\frac{d E}{d z}=\frac{E^{g}}{l_{E}}, & \frac{d \phi}{d z}=\frac{\phi^{g}}{l_{\phi}}, & \frac{d \rho}{d z}=\frac{\rho^{g}}{l_{\rho}},
\end{array}
$$

In addition we define the local ion gyroradius $\rho_{i}(z)$, the local electron Debye length $\lambda_{\text {De }}(z)$, as well as the local collisional lengths $l_{i}(z)$ ("ionization length"), $l_{r}(z)$ ("recombination length"), $l_{i r}(z)$ ("combined ionization and recombination length"), $l_{c x}(z)$ ("charge-exchange mean free path") and $\bar{l}(z)$ (combined CX-ionization and recombination length") by

$$
\begin{equation*}
\rho_{i}=\frac{u_{z}}{\omega}=\frac{u_{z} m_{i}}{Z e B} \quad \lambda_{D e}=\sqrt{\frac{\varepsilon_{0} k T_{e^{*}}}{n_{e} e^{2}}} \tag{3.4}
\end{equation*}
$$

and

$$
\begin{array}{ll}
\frac{1}{l_{i}}=\frac{v_{i} n_{e}}{u_{z} n_{i}}, & \frac{1}{l_{r}}=\frac{\kappa n_{e}}{u_{z}} \\
\frac{1}{l_{i r}}=\frac{v_{i r}}{u_{z}}=\frac{1}{l_{i}}-\frac{1}{l_{r}}, & \frac{1}{l_{c x}}=\frac{v_{c x}}{u_{z}}  \tag{3.5}\\
\frac{1}{\bar{l}}=\frac{\bar{v}}{u_{z}}=\frac{1}{l_{c x}}+\frac{1}{l_{i r}}=\frac{1}{l_{c x}}+\frac{1}{l_{i}}-\frac{1}{l_{r}}
\end{array}
$$

respectively. These lengths may be considered to be the "natural" lengths existing in our problem. Let us also define the "dominant" (i.e., smallest) collision lengths as

$$
\begin{equation*}
l_{c}^{\min }(z)=\min \left\{\left|l_{i r}\right|,|\bar{l}|\right\} . \tag{3.6}
\end{equation*}
$$

With the definitions (3.3), Eqs. (2.1), (2.3) - (2.5) and (2.9) - (2.11) can be rewritten in the gradient-length form

$$
\begin{align*}
& \frac{1}{n_{i}} \frac{n_{i}^{g}}{l_{n i}}+\frac{1}{u_{z}} \frac{u_{z}^{g}}{l_{u z}}=\frac{1}{l_{i r}},  \tag{3.7}\\
& \frac{u_{x}^{g}}{l_{u x}}+\frac{u_{x}}{\bar{l}}=\frac{\sin \alpha}{\rho_{i}} u_{y},  \tag{3.8}\\
& \frac{u_{y}^{g}}{l_{u y}}+\frac{u_{y}}{\bar{l}}=\frac{\cos \alpha}{\rho_{i}} u_{z}-\frac{\sin \alpha}{\rho_{i}} u_{x},  \tag{3.9}\\
& \frac{1}{u_{z}} \frac{u_{z}^{g}}{l_{u z}}+\frac{1}{\bar{l}}=\frac{Z e E}{m_{i} u_{z}^{2}}-\frac{\cos \alpha}{\rho_{i}} \frac{u_{y}}{u_{z}}-\frac{1}{n_{i} m_{i} u_{z}^{2}} \frac{p_{i}^{g}}{l_{p i}},  \tag{3.10}\\
& \frac{T_{e^{*}}}{n_{e}} \frac{n_{e}^{g}}{l_{n e}}=-\frac{e}{k} E,  \tag{3.11}\\
& \frac{E^{g}}{l_{E}}=\frac{e}{\varepsilon_{0}}\left(Z n_{i}-n_{e}\right), \tag{3.12}
\end{align*}
$$

and

$$
\begin{align*}
& \frac{1}{p_{i}} \frac{p_{i}^{g}}{l_{p i}}=\frac{\gamma}{n_{i}} \frac{n_{i}^{g}}{l_{n i}} .  \tag{3.13}\\
& \frac{\phi^{g}}{l_{E}}=-E, \tag{3.14}
\end{align*}
$$

respectively, and differentiating (2.14) we find

$$
\begin{equation*}
\frac{\rho^{g}}{l_{\rho}}=e\left(Z \frac{n_{i}^{g}}{l_{n i}}-\frac{n_{e}^{g}}{l_{n e}}\right) \tag{3.15}
\end{equation*}
$$

For later use we introduce the additional definitions

$$
\begin{array}{ll}
\frac{1}{\overline{l_{u x}}}=\frac{1}{u_{x}} \frac{u_{x}^{g}}{l_{u x}}+\frac{1}{\bar{l}}, & \frac{1}{\overline{\bar{l}_{u y}}}=\frac{1}{u_{y}} \frac{u_{y}^{g}}{l_{u y}}+\frac{1}{\bar{l}}, \\
c_{e}^{2}=\frac{Z k T_{e^{*}}}{m_{i}}, & c_{i}^{2}=\frac{\gamma k T_{i}}{m_{i}},  \tag{3.17}\\
c^{2}=c_{e}^{2}+c_{i}^{2}=\frac{k}{m_{i}}\left(Z T_{e^{*}}+\gamma T_{i}\right),
\end{array}
$$

and

$$
\begin{equation*}
\hat{\rho}=\frac{\rho}{Z e n_{i}-\rho}=\frac{\rho}{e n_{e}}, \tag{3.18}
\end{equation*}
$$

Equations (3.7) - (3.15) represent a system of 9 equations interrelating the 9 gradient lengths $l_{u x}(z), l_{u y}(z)$, $l_{u z}(z), l_{n e}(z), l_{n i}(z), l_{p i}(z), l_{E}(z), l_{\phi}(z), l_{\rho}(z)$ and the

9 scalar functions $u_{x}(z), u_{y}(z), u_{z}(z), n_{e}(z), n_{i}(z)$, $p_{i}(z), E(z), \phi(z)$ and $\rho(z)$, which are the solution functions of the 9 original basic equations (2.1), (2.3) (2.5), (2.9) - (2.11), (2.13) and (2.14). In particular, the gradient lengths can be expressed in terms of the solution functions as follows:

$$
\begin{align*}
& \frac{u_{x}^{g}}{l_{u x}}=\frac{\sin \alpha}{\rho_{i}} u_{y}-\frac{u_{x}}{\bar{l}},  \tag{3.19}\\
& \frac{u_{y}^{g}}{l_{u y}}=\frac{\cos \alpha}{\rho_{i}} u_{z}-\frac{\sin \alpha}{\rho_{i}} u_{x}-\frac{u_{y}}{\bar{l}},  \tag{3.20}\\
& u_{z}^{g} / l_{u z} \\
& =\frac{u_{z} u_{z}^{2}}{u_{z}^{2}-c_{i}^{2}}\left(\frac{Z e E}{m_{i} u_{z}^{2}}-\frac{\cos \alpha}{\rho_{i}} \frac{u_{y}}{u_{z}}-\frac{1}{l_{i r}} \frac{c_{i}^{2}}{u_{z}^{2}}-\frac{1}{\bar{l}}\right),  \tag{3.21}\\
& \frac{n_{e}^{g}}{l_{n e}}=-n_{e} \frac{e E}{k T_{e^{*}}},  \tag{3.22}\\
& \frac{n_{i}^{g}}{l_{n i}}=\frac{n_{i} u_{z}^{2}}{u_{z}^{2}-c_{i}^{2}}\left(\frac{\cos \alpha}{\rho_{i}} \frac{u_{y}}{u_{z}}-\frac{Z e E}{m_{i} u_{z}^{2}}+\frac{1}{l_{i r}}+\frac{1}{\bar{l}}\right),  \tag{3.23}\\
& \frac{p_{i}^{g}}{l_{p i}}=\frac{\gamma p_{i} u_{z}^{2}}{u_{z}^{2}-c_{i}^{2}}\left(\frac{\cos \alpha}{\rho_{i}} \frac{u_{y}}{u_{z}}-\frac{Z e E}{m_{i} u_{z}^{2}}+\frac{1}{l_{i r}}+\frac{1}{\bar{l}}\right),  \tag{3.24}\\
& \frac{E^{g}}{l_{E}}=\frac{\rho}{\varepsilon_{0}},  \tag{3.25}\\
& \frac{\phi^{g}}{l_{\phi}^{g}}=-E, \tag{3.26}
\end{align*}
$$

With the help of Eqs. (3.19), (3.20) and (3.22)-(3.26), Eq. (3.21) can be cast into the following form, which will be used below:

$$
\begin{align*}
& \frac{1}{u_{z}} \frac{u_{z}^{g}}{l_{u z}}\left(1-\frac{c^{2}+c_{e}^{2} \hat{\rho}}{u_{z}^{2}}\right)-\frac{c_{e}^{2}}{u_{z}^{2}}\left(\frac{1}{n_{i}} \frac{n_{i}^{g}}{l_{n i}}-\frac{1}{n_{e}} \frac{n_{e}^{g}}{l_{n e}}\right) \\
& \quad+\frac{c_{e}^{2}}{u_{z}^{2}} \frac{\lambda_{D e}^{2}}{l_{E} l_{n i} l_{n e}} \frac{n_{i}^{g}}{n_{i}} \frac{n_{e}^{g}}{n_{e}}  \tag{3.27}\\
& =-\frac{c^{2}+c_{e}^{2} \hat{\rho}}{u_{z}^{2}} \frac{1}{l_{i r}}-\frac{1}{\bar{l}}-\frac{\bar{l}_{u y} \cos ^{2} \alpha}{\rho_{i}^{2}+\bar{l}_{u x} \bar{l}_{u y} \sin ^{2} \alpha},
\end{align*}
$$

## 4. Gradient-length analysis of the MPWT

### 4.1. MPS entrance

In the A3S limit, both the CPS and the MPS are quasineutral, so that in Eq. (3.27) we set $\hat{\rho}=0$.
(i) From the CPS side, the relations between the gradient lengths are

$$
\begin{equation*}
\left|l_{u x}\right|,\left|l_{u y}\right|,\left|l_{u z}\right|=O\left(l_{c}^{c h}\right) \gg \rho_{i} . \tag{4.1}
\end{equation*}
$$

From (3.27) we find

$$
\begin{align*}
& \frac{1}{u_{z}} \frac{u_{z}^{g}}{l_{u z}}\left(1-\frac{c^{2}}{u_{z}^{2}}\right)+\frac{\cos ^{2} \alpha}{\sin ^{2} \alpha} \frac{1}{u_{x}} \frac{u_{x}^{g}}{l_{u x}} \\
& \quad=-\frac{1}{\sin ^{2} \alpha} \frac{1}{l_{c x}}-\left(\frac{c^{2}}{u_{z}^{2}}+\frac{1}{\sin ^{2} \alpha}\right) \frac{1}{l_{i r}} \tag{4.2}
\end{align*}
$$

From (3.9) and (4.1) it follows that

$$
\begin{equation*}
l_{u x}=l_{u z}, \tag{4.3}
\end{equation*}
$$

Then from (4.2) we find

$$
\begin{equation*}
\frac{1}{u_{z}} \frac{u_{z}^{g}}{l_{u z}}\left(\frac{c^{2} \sin ^{2} \alpha}{u_{z}^{2}}-1\right)=\frac{1}{l_{c x}}+\left(\frac{c^{2} \sin ^{2} \alpha}{u_{z}^{2}}+1\right) \frac{1}{l_{i r}} . \tag{4.4}
\end{equation*}
$$

If the marginal form of the Bohm-Chodura condition,

$$
\begin{equation*}
u_{z}^{2}=c^{2} \sin ^{2} \alpha, \tag{4.5}
\end{equation*}
$$

is fulfilled, we have $l_{u x}=0$. This means that the derivative of the ion velocity (and the electric field) has a singularity. The point where the marginal Bohm-Chodura condition is fulfilled can be considered as the MPS entrance as seen from the CPS side.
(ii) Close to the MPS entrance, we have from the MPS side

$$
\begin{equation*}
\left|l_{u x}\right|,\left|l_{u y}\right|,\left|l_{u z}\right|, \rho_{i} \ll\left|l_{i r}\right|,\left|l_{c x}\right|, \tag{4.6}
\end{equation*}
$$

The quasineutrality condition, $\hat{\rho}=0$, is again fulfilled.
From Eq. (3.27) we have

$$
\begin{equation*}
\frac{1}{\tilde{l}_{u z}}\left(1-\frac{c^{2}}{u_{z}^{2}}\right)=-\frac{\tilde{l}_{u y} \cos ^{2} \alpha}{\rho_{i}^{2}+\tilde{l}_{u x} \tilde{l}_{u y} \sin ^{2} \alpha} \tag{4.7}
\end{equation*}
$$

where

$$
\begin{equation*}
\frac{1}{\tilde{l}_{u j}}=\frac{u_{j}^{g}}{u_{j}} \frac{1}{l_{u j}} \quad \text { and } \quad \frac{1}{\tilde{l}_{\rho}}=\frac{\rho^{g}}{\rho} \frac{1}{l_{\rho}} . \tag{4.8}
\end{equation*}
$$

It can be shown that

$$
\begin{equation*}
\tilde{l}_{u x}=\tilde{l}_{u y}=\tilde{l}_{u z}, \tag{4.9}
\end{equation*}
$$

with which straightforward calculations lead to the result

$$
\begin{equation*}
\frac{\rho_{i}^{2}}{\tilde{l}_{u z}}=\frac{\sin ^{2} \alpha}{\cos ^{2} \alpha}\left(1-\frac{c^{2} \sin ^{2} \alpha}{u_{z}^{2}}\right) \tag{4.10}
\end{equation*}
$$

Hence at

$$
\begin{equation*}
u_{z}^{2} \rightarrow c^{2} \sin ^{2} \alpha \quad\left(u_{z}^{2}>c^{2} \sin ^{2} \alpha\right) \tag{4.11}
\end{equation*}
$$

we have

$$
\begin{equation*}
l_{u z} \rightarrow \infty, \tag{4.12}
\end{equation*}
$$

which means that on the scale of the ion gyroradius the $z$ velocity component tends monotonically towards a constant value. The same behavior can be shown to be true for the other physical quantities as well. The relation (4.11) is known as the non-marginal form of the Bohm-Chodura condition for the MPS entrance.

### 4.2. DS entrance

For the definition of the DS entrance, we can again use Eq. (3.27).
(i) For the analysis of the MPS-DS transition from the MPS side, we again assume, besides quasineutrality, the length relations (4.6). From (3.9), (3.10) and (3.27) we then obtain

$$
\begin{equation*}
\tilde{l}_{u x}=\frac{\rho_{i} u_{x}}{u_{y} \sin \alpha}, \tag{4.13}
\end{equation*}
$$

$$
\begin{gather*}
\tilde{l}_{u y}=\frac{\rho_{i} u_{y}}{u_{z} \cos \alpha-u_{x} \sin \alpha},  \tag{4.14}\\
\frac{1}{\tilde{l}_{u z}}\left(1-\frac{c^{2}}{u_{z}^{2}}\right)=\frac{\tilde{l}_{u y} \cos ^{2} \alpha}{\rho_{i}^{2}+\tilde{l}_{u x} \tilde{l}_{u y} \sin ^{2} \alpha}, \tag{4.15}
\end{gather*}
$$

Substitution of (4.13) and (4.14) into (4.15) yields

$$
\begin{equation*}
\frac{u_{z}^{g}}{u_{z}} \frac{1}{l_{u z}}\left(\frac{c^{2}}{u_{z}^{2}}-1\right)=\cos \alpha \frac{\omega u_{y}}{u_{z}^{2}} \tag{4.16}
\end{equation*}
$$

The condition

$$
\begin{equation*}
u_{z}^{2}=c^{2} \tag{4.17}
\end{equation*}
$$

is the Bohm condition in the marginal form, defining the singularity point where $l_{u z}=0$. This point is defined as the DS entrance in the A3S limit
(ii) From the DS side the quasineutrality is broken ( $\rho \neq 0$ ), and the gradient lengths satisfy the condition

$$
\begin{equation*}
\left|l_{u x}\right|,\left|l_{u y}\right|,\left|l_{u z}\right|,\left|l_{\rho}\right|,\left|l_{E}\right| \ll \rho_{i},\left|l_{i r}\right|,\left|l_{c x}\right|, \tag{4.18}
\end{equation*}
$$

From Eq. (3.27) we obtain

$$
\begin{equation*}
\frac{1}{\tilde{l}_{u z}}\left(1-\frac{c^{2}}{u_{z}^{2}}\right)=\hat{\rho} \frac{c_{e}^{2}}{u_{z}^{2}}\left(\frac{1}{\tilde{l}_{u z}}+\frac{1}{\tilde{l}_{\rho}}\right) \tag{4.19}
\end{equation*}
$$

Using Eqs. (3.11), (3.12) and (3.18), we obtain from (4.19)

$$
\begin{equation*}
1-\frac{c^{2}}{u_{z}^{2}}=\frac{c_{e}^{2}}{u_{z}^{2}} \frac{\lambda_{D}^{2}}{l_{E}^{2}}\left(1+\frac{\tilde{l}_{u z}}{\tilde{l}_{\rho}}\right) . \tag{4.20}
\end{equation*}
$$

where the relation

$$
\begin{equation*}
-\tilde{l}_{n e} \simeq \tilde{l}_{E} \tag{4.21}
\end{equation*}
$$

has been used, where $\tilde{l}_{n e}$ and $\tilde{l}_{E}$ are defined in analogy with (4.8). The lengths $l_{u z}$ and $l_{\rho}$ should have the same order, i.e. $l_{u z} \simeq l_{\rho}$. From Eq. (4.20) we obtain that at the point where

$$
\begin{equation*}
u_{z}^{2} \rightarrow c^{2} \quad\left(u_{z}^{2}>c^{2}\right) \tag{4.22}
\end{equation*}
$$

we have

$$
\begin{equation*}
l_{E}^{2} \rightarrow \infty . \tag{4.23}
\end{equation*}
$$

This means that on the scale of the Debye length the electric field on the DS side tends asymptotically towards a constant value. The same behavior can be shown to be true for the other physical quantities as well.

## 5. Conclusion

A new method for analyzing the magnetized plasma-wall transition (MPWT), based on local and characteristic gradient-length scales, has been introduced (Sec. 3). By means of this new method, the CPS-MPS and MPS-DS transitions have been investigated (Sec. 4) for a fairly general MPWT model (Sec. 2). It has been found for the first time that the MPS-CPS interface (MPS entrance) can be defined as a surface where the electric field from the CPS side has a singularity, quite in analogy with the CPS-DS transition of the unmagnetized PWT. Regarding the MPS-DS interface, previous results have been recovered. The present work adds a significant contribution to the analysis and understanding of the MPWT.

## Acknowledgments

This work has been supported by the Austrian Research Fund (FWF) through Project P19235-N16, by the Georgian Research Fund through Project GNSF 69/07, by the European Communities under the Contract of Association between EURATOM and the Austrian Academy of Sciences, and by the Higher Education Commission of Pakistan. It was carried out within the framework of the European Fusion Development Agreement. The views and opinions expressed herein do no necessarily reflect those of the European Commission.

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