

JT-60SAに向けた複合実時間制御と運転シナリオの開発  
**Development of integrated real-time controls and operation scenarios  
 for JT-60SA**

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The JT-60SA experiment program [1] is aimed at supporting ITER and providing the physics basis and guidelines for DEMO design having broad conceptual spectrum. In achieving mission goals of ITER and designing DEMO, control, especially real-time control, of physics parameters play an essential role. Successful realization of ITER standard operation at  $Q=P_e/P_{ex}=10$  needs control of burning state where self heating by fusion alpha particle ( $P_e$ ) exceeds external heating power ( $P_{ex}$ ) for control. In realizing ITER steady-state operation at  $Q=5$  where large bootstrap current at high plasma pressure (normalized beta  $\beta_N$ ) contributes to achieve full non-inductive current drive (full-CD) of plasma current, controls of MHD stability at high beta as well as full-CD state are required.

JT-60SA is designed to contribute to development of the control issues above [2]. We have been developing an integrated real-time control system to be applied to and examined in the JT-60SA experiment. The development is carried out on the TOPICS integrated code suite where thermal transport is modeled as CDBM turbulent transport that reasonably well explains the JT-60U experiment [3]. Plasma density profile and pedestal temperature is prescribed to give thermal energy confinement time agrees with the H98(y,2) scaling. The controller under development is a multi-input multi-output controller having a matrix of PID controllers and is flexibly extensible to control of various physics parameters:

$$\begin{pmatrix} P_1(t+dt) \\ P_2(t+dt) \\ \vdots \end{pmatrix} = \begin{pmatrix} P_{PP1}(t+dt) \\ P_{PP2}(t+dt) \\ \vdots \end{pmatrix} + \mathbf{M} \begin{pmatrix} \beta_{Nref}(t) - \beta_N(t) \\ V_{loopref}(t) - V_{loop}(t) \\ \vdots \end{pmatrix},$$

where  $\mathbf{M} \equiv \begin{pmatrix} PID_{11} & PID_{12} & \cdots \\ PID_{21} & PID_{22} & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix}$ . (1)

The controller (1) feedback controls  $\beta_N$  to its

given reference  $\beta_{Nref}$  and loop voltage  $V_{loop}$  to its reference  $V_{loopref}$  using combination of command output  $P_1$  and  $P_2$  of actuators through PID matrix  $\mathbf{M}$ . The first term of the right-hand-side of eq (1),  $P_{PP1}$  and  $P_{PP2}$ , is the pre-programmed output to be given prior to control. Our previous work [4] investigated simultaneous controllability of  $\beta_N$  and  $V_{loop}$  (essential parameter to full-CD) in real-time in JT-60SA as well as dependence of the controllability on plasma density in TOPICS simulations.

In this study, we have explored integrated real-time control of 3 physics parameters essential in steady sustainment of high beta plasma, namely  $\beta_N$ ,  $V_{loop}$  and the minimum of the safety factor profile  $q_{min}$ . This  $q_{min}$  determines the existence of the low-q rational surface at which steep pressure gradient is prone to provoke MHD instability. These parameters,  $\beta_N$ ,  $V_{loop}$  and  $q_{min}$  are controlled by heating power, total CD power and differential current drive power (off-axis CD power minus on-axis CD power), respectively.

We have also developed control scheme of alpha heating where the alpha heating is simulated (numerically here and experimentally in JT-60SA DD operation) using exclusively allocated part of EC+NB heating power. Although study of “real” burning plasma must wait for ITER DT campaign, we hope to investigate a part of burning plasma behavior and develop a controller with this scheme prior to ITER experiment. We show the controllability of the simulated alpha heating at H-mode entry in JT-60SA.

[1] Y. Kamada, Nucl. Fusion **53** (2013) 104010

[2] JT-60SA Research Plan Version 3.2, Chapter 3; <http://www-jt60.naka.jaea.go.jp/jt60/pdf/JT-60SA%20Research%20Plan%20Ver.3.2.pdf>

[3] J. Garcia, N. Hayashi et al., Nucl. Fusion **54** (2014) 093010

[4] T. Suzuki et al., 40<sup>th</sup> EPS Conf. (Espoo, 2013) P2.136